

# Print of all equations for FIDISOL/CADSOL

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## Clear Variables

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## Input Equations of Motion

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## Modification to the functions

Here we will write the *ansatz* function as FIDISOL/CADSOL wants. We implement as well the radial coordinate transformation  $\bar{x} = \frac{x}{1+x}$  which changes the first and second radial derivative of the functions.

### Ansatz functions

```
In[ ]:= F1[x, θ] = U1;  
F2[x, θ] = U2;  
Fθ[x, θ] = U3;  
W[x, θ] = U4;  
  
In[ ]:= F1(1,0)[x, θ] = ff2 U1x;  
F2(1,0)[x, θ] = ff2 U2x;  
Fθ(1,0)[x, θ] = ff2 U3x;  
W(1,0)[x, θ] = ff2 U4x;  
  
In[ ]:= F1(2,0)[x, θ] = ff4 U1xx - 2 ff3 U1x;  
F2(2,0)[x, θ] = ff4 U2xx - 2 ff3 U2x;  
Fθ(2,0)[x, θ] = ff4 U3xx - 2 ff3 U3x;  
W(2,0)[x, θ] = ff4 U4xx - 2 ff3 U4x;  
  
In[ ]:= F1(1,1)[x, θ] = ff2 U1xy;  
F2(1,1)[x, θ] = ff2 U2xy;  
Fθ(1,1)[x, θ] = ff2 U3xy;  
W(1,1)[x, θ] = ff2 U4xy;
```

```
In[1]:= F1^(0,1)[x, θ] = U1y;
F2^(0,1)[x, θ] = U2y;
F0^(0,1)[x, θ] = U3y;
W^(0,1)[x, θ] = U4y;

In[2]:= F1^(0,2)[x, θ] = U1yy;
F2^(0,2)[x, θ] = U2yy;
F0^(0,2)[x, θ] = U3yy;
W^(0,2)[x, θ] = U4yy;

In[3]:= H[x] := H;
H'[x] := derH;
H''[x] := der2H;
S[x] := S;
S'[x] := 2 x;
S''[x] := 2;
```

## Trigonometric functions

```
In[1]:= Unprotect[Sin];
Unprotect[Cos];
Unprotect[Cot];
Unprotect[Csc];
Sin[θ] = sn;
Cos[θ] = cs;
Cos[2 θ] = cs2;
Cot[θ] = cs / sn;
Csc[θ] = csc;
```

## Convert E\*\*x to dExp(x)

```
In[1]:= Unprotect[Power];
Power /: Format[Power[E, x_], FortranForm] := dExp[x]
Protect[Power];
```

## Set of the width of the output

For some reason, Fortran does not like very long expressions.

```
In[1]:= SetOptions[$Output, PageWidth → 65];
```

# Print Equations

## Equation 1:

```
In[1]:= FortranForm[Simplify[Eq1]]
Out[1]//FortranForm=
(sn*(-((dExp(2*U2 - 2*U3)*S**2*sn**3*
- (ff**4*H*S*U4xxx2 + U4y**2))/x) -
- 2*H*(4*ff**3*H*S*sn*U1xxx -
- 2*ff**4*H*S*sn*(U1xx - U2x*U3x)*x +
- 2*(-(sn*U1yy) + cs*U3y + sn*U2y*U3y)*x +
- ff**2*sn*(2*H*S*U2x + derH*S*(-U1x + U2x)*x -
- 2*H*(U1x + U2x - U3x)*x**2)))/(4.*H**2*S)
```

## Equation 2:

```
In[2]:= FortranForm[Simplify[Eq2]]
Out[2]//FortranForm=
(sn*(dExp(2*U2 - 2*U3)*S**3*sn**3*
- (ff**4*H*S*U4xxx2 + U4y**2) +
- 2*H*x*(-2*ff**3*H*S**2*sn*U2xxx +
- ff**4*H*S**2*sn*(U2xxx2 + U2xx + U2x*U3x)*x +
- ff**2*S*sn*(H*S*U2x + derH*S*U2xxx +
- H*(2*U2x + U3x)*x**2) +
- x*(cs*S*(2*U2y + U3y) - H*sn*x**2 +
- S*sn*(-1 + 2*H + U2y**2 + U2yy + U2y*U3y +
- derH*x))))/(2.*H**2*S**2*x**2)
```

## Equation 3:

```
In[3]:= FortranForm[Simplify[Eq3]]
Out[3]//FortranForm=
-((dExp(2*U2 - 2*U3)*S*sn**3*
- (ff**4*H*S*U4xxx2 + U4y**2))/(H**2*x)) -
- 4*ff**3*sn*U3xxx +
- 2*ff**4*sn*(U2xx*U3x + U3xxx2 + U3xx)*x +
- (2*ff**2*sn*(S*(U2x + 2*U3x) - U2xxx**2))/S +
- (derH*sn*(-x**2 + S*(3 + ff**2*(U2x + 3*U3x)*x)))/
- (H*S) + (x*(S*(der2H*S*sn + 2*cs*U3y +
- 2*sn*(U2y*U3y + U3y**2 + U3yy)) +
- 2*H*sn*(-S + x**2)))/(H*S**2)
```

## Equation 4:

```
In[•]:= FortranForm[Simplify[Eq4]]
Out[•]//FortranForm=
(sn*x*(-2*ff**3*H*S*sn*U4x*x +
- ff**4*H*S*sn*(3*U2x*U4x - U3x*U4x + U4xx)*x +
- 3*cs*U4y*x + sn*(3*U2y*U4y - U3y*U4y + U4yy)*x -
- ff**2*H*sn*U4x*(S - 5*x**2))/(H*S)
```

## Constraint Equation 1:

```
In[•]:= FortranForm[Simplify[ConstrainEq1]]
Out[•]//FortranForm=
(dExp(2*U2)*S**3*sn**3*(ff**4*H*S*U4x**2 - U4y**2) -
- dExp(2*U3)*H*x*(-4*ff**3*H*S**2*sn*(U2x + U3x)*x +
- 2*ff**4*H*S**2*sn*
- (U2x**2 + U2xx + U3x**2 - 2*U1x*(U2x + U3x) +
- U3xx)*x + x*
- (der2H*S**2*sn -
- 2*S*(2*cs*(-U1y + U2y) +
- sn*(-1 + 3*H + U2y**2 + U2yy + U3y**2 -
- 2*U1y*(U2y + U3y) + U3yy)) + 4*H*sn*x**2)\ \
- + 2*ff**2*H*S*sn*
- (-2*S*(U1x - U3x) + (U2x - 3*U3x)*x**2) +
- derH*S*sn*(-3*x**2 +
- S*(3 + ff**2*(-2*U1x + U2x + 3*U3x)*x)))/
- (2.*dExp(2*(U1 + U3))*H*S**2*sn*x**2)
```

## Constraint Equation 2:

```
In[•]:= FortranForm[Simplify[ConstrainEq2]]
Out[•]//FortranForm=
(dExp(2*U2)*ff**2*S**3*sn**3*U4x*U4y +
- dExp(2*U3)*x*(derH*S*sn*(U1y - U3y)*x +
- 2*H*(cs*ff**2*S*(U1x - U2x)*x + 2*sn*U3y*x**2 +
- S*sn*(U1y + ff**2*U1y*(U2x + U3x)*x -
- ff**2*(U2xy - U1x*U2y + U2x*U2y + U3xy)*x +
- U3y*(-1 + ff**2*(U1x - U3x)*x)))/
- (2.*dExp(2*(U1 + U3))*H*S**2*sn*x**2)
```

## Ricci Scalar:

```
In[=]:= FortranForm[Simplify[R]]
Out[=]//FortranForm=
(dExp(2*U2)*S**2*sn**2*U4y**2 -
 - 4*dExp(2*U3)*H**2*x*
 - (x - 2*ff**3*S*(U1x + U2x + U3x)*x +
 - ff**4*S*(U1xx + U2x**2 + U2xx + U2x*U3x + U3x**2 +
 - U3xx)*x + ff**2*
 - (S*(U2x + 2*U3x) + (U1x + 2*U2x)*x**2)) -
 - H*(-(dExp(2*U2)*ff**4*S**3*sn**2*U4x**2) +
 - dExp(2*U3)*x**2*
 - (4*(-1 + U1yy + U2y**2 + U2yy + U2y*U3y + U3y**2 +
 - (cs*(2*U2y + U3y))/sn + U3yy) + 2*derH*x) +
 - 2*dExp(2*U3)*S*x*
 - (der2H*x + derH*
 - (3 + ff**2*(U1x + 2*U2x + 3*U3x)*x))))/
 - (2.*dExp(2*(U1 + U3))*H*S*x**2)
```

## Kretschmann Scalar:

Only print this one when you need it, because it is a train of an expression.

```
In[=]:= FortranForm[KretschmanScalar];
```

## Print Jacobian

Here we compute the derivatives of the equations of motion w.r.t the several *ansatz* functions and its first and second derivatives.

### Equation 1

```
In[=]:= Eq1Uxx1 = D[Eq1, U1xx];
Eq1Uxy1 = D[Eq1, U1xy];
Eq1Uyy1 = D[Eq1, U1yy];
Eq1Ux1 = D[Eq1, U1x];
Eq1Uy1 = D[Eq1, U1y];
Eq1U1 = D[Eq1, U1];
```

```
In[=]:= FortranForm[Simplify[Eq1Uxx1]]
Out[=]//FortranForm=
ff**4*sn**2*x
```

```
In[=]:= FortranForm[Simplify[Eq1Uxy1]]
Out[=]//FortranForm=
0
```

```

In[=]:= FortranForm[Simplify[Eq1Uyy1]]
Out[=]//FortranForm=
(sn**2*x)/(H*S)

In[=]:= FortranForm[Simplify[Eq1Ux1]]
Out[=]//FortranForm=
( ff**2*sn**2*x*(derH*S + 2*H*(-2*ff*S + x)))/(2.*H*S)

In[=]:= FortranForm[Simplify[Eq1Uy1]]
Out[=]//FortranForm=
0

In[=]:= FortranForm[Simplify[Eq1U1]]
Out[=]//FortranForm=
0

In[=]:= Eq1Uxx2 = D[Eq1, U2xx];
Eq1Uxy2 = D[Eq1, U2xy];
Eq1Uyy2 = D[Eq1, U2yy];
Eq1Ux2 = D[Eq1, U2x];
Eq1Uy2 = D[Eq1, U2y];
Eq1U2 = D[Eq1, U2];

In[=]:= FortranForm[Simplify[Eq1Uxx2]]
Out[=]//FortranForm=
0

In[=]:= FortranForm[Simplify[Eq1Uxy2]]
Out[=]//FortranForm=
0

In[=]:= FortranForm[Simplify[Eq1Uyy2]]
Out[=]//FortranForm=
0

In[=]:= FortranForm[Simplify[Eq1Ux2]]
Out[=]//FortranForm=
-( ff**2*sn**2*(derH*S*x +
- 2*H*(S + ff**2*S*U3*x*x - x**2)))/(2.*H*S)

In[=]:= FortranForm[Simplify[Eq1Uy2]]
Out[=]//FortranForm=
-((sn**2*U3*y*x)/(H*S))

In[=]:= FortranForm[Simplify[Eq1U2]]
Out[=]//FortranForm=
-(dExp(2*U2 - 2*U3)*S*sn**4*(ff**4*H*S*U4*x**2 + U4*y**2))/(
- (2.*H**2*x)

```

```

In[1]:= Eq1Uxx3 = D[Eq1, U3xx];
Eq1Uxy3 = D[Eq1, U3xy];
Eq1Uyy3 = D[Eq1, U3yy];
Eq1Ux3 = D[Eq1, U3x];
Eq1Uy3 = D[Eq1, U3y];
Eq1U3 = D[Eq1, U3];

In[2]:= FortranForm[Simplify[Eq1Uxx3]]
Out[2]//FortranForm=
0

In[3]:= FortranForm[Simplify[Eq1Uxy3]]
Out[3]//FortranForm=
0

In[4]:= FortranForm[Simplify[Eq1Uyy3]]
Out[4]//FortranForm=
0

In[5]:= FortranForm[Simplify[Eq1Ux3]]
Out[5]//FortranForm=
-((ff**2*sn**2*x*(ff**2*S*U2x + x))/S)

In[6]:= FortranForm[Simplify[Eq1Uy3]]
Out[6]//FortranForm=
-((sn*(cs + sn*U2y)*x)/(H*S))

In[7]:= FortranForm[Simplify[Eq1U3]]
Out[7]//FortranForm=
(dExp(2*U2 - 2*U3)*S*sn**4*(ff**4*H*S*U4x**2 + U4y**2))/(
2.*H**2*x)

In[8]:= Eq1Uxx4 = D[Eq1, U4xx];
Eq1Uxy4 = D[Eq1, U4xy];
Eq1Uyy4 = D[Eq1, U4yy];
Eq1Ux4 = D[Eq1, U4x];
Eq1Uy4 = D[Eq1, U4y];
Eq1U4 = D[Eq1, U4];

In[9]:= FortranForm[Simplify[Eq1Uxx4]]
Out[9]//FortranForm=
0

In[10]:= FortranForm[Simplify[Eq1Uxy4]]
Out[10]//FortranForm=
0

```

```
In[8]:= FortranForm[Simplify[Eq1Uyy4]]
Out[8]//FortranForm=
0

In[9]:= FortranForm[Simplify[Eq1Ux4]]
Out[9]//FortranForm=
-(dExp(2*U2 - 2*U3)*ff**4*S**2*sn**4*U4x)/(2.*H*x)

In[10]:= FortranForm[Simplify[Eq1Uy4]]
Out[10]//FortranForm=
-(dExp(2*U2 - 2*U3)*S*sn**4*U4y)/(2.*H**2*x)

In[11]:= FortranForm[Simplify[Eq1U4]]
Out[11]//FortranForm=
0
```

Equation 2

Equation 3

Equation 4